



Understanding Singular Value Decomposition

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Outline

- Some prerequisite results
- Singular value decomposition theorem
- Relationship between SVD and EVD
- Economy-sized form and outer product form of SVD
- Matrix norms and singular values
- SVD and linear least squares



Some Prerequisite Results

Result 1: Suppose that $rank(A_{m \times n}) = r$, then $r(A^T A) = r(AA^T) = r$

Proof: Let's prove if $r(A_{m \times n}) = r$, then $r(A^T A) = r(A) = r$

Given an $\mathbf{x} \in \mathbb{R}^{n \times 1}$, if $A\mathbf{x} = \mathbf{0} \implies A^T A\mathbf{x} = \mathbf{0}$

Given an $\mathbf{x} \in \mathbb{R}^{n \times 1}$, if $A^T A\mathbf{x} = \mathbf{0}$

\downarrow

$\mathbf{x}^T A^T A\mathbf{x} = 0$

\downarrow

$(A\mathbf{x})^T A\mathbf{x} = 0 \implies A\mathbf{x} = \mathbf{0}$

$\implies \begin{cases} A^T A\mathbf{x} = \mathbf{0} \\ A\mathbf{x} = \mathbf{0} \end{cases}$ have the same solutions

\downarrow

$r(A^T A) = r(A) = r$

Following a similar way, we can prove $r(AA^T) = r(A) = r$



Some Prerequisite Results

Result 2: If A is an $n \times n$ real symmetric matrix and $r(A)=r$, then A has and only has r non-zero eigen-values

Proof: Since A is an $n \times n$ real symmetric matrix, A can be diagonally decomposed as

$$A = P \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} P^{-1}, \text{ where } P \text{ is an invertible matrix and } \lambda_i\text{'s are } A\text{'s } n \text{ eigen-values}$$

Since multiplied by an invertible matrix, a matrix's rank remains

$$r \left(\begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \right) = r(A) = r \rightarrow \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \text{ has } r \text{ non-zeros diagonal entries}$$



Some Prerequisite Results

Result 3: Suppose A is an $m \times n$ matrix, then

$(A^T A)_{n \times n}$ and $(AA^T)_{m \times m}$ are both positive semi-definite matrices

Proof:

$$\forall \mathbf{x} \neq \mathbf{0}, 0 \leq (\mathbf{Ax})^T (\mathbf{Ax}) = \mathbf{x}^T A^T A \mathbf{x}$$



$(A^T A)_{n \times n}$ is positive semi-definite

Following a similar way, we can prove $(AA^T)_{m \times m}$ is also positive semi-definite



Some Prerequisite Results

Result 4: Suppose A is an $m \times n$ matrix, then

$(A^T A)_{n \times n}$ and $(AA^T)_{m \times m}$ have the same nonzero eigen-values

Proof:

Suppose that λ is the eigen-value of $(A^T A)_{n \times n}$ and \mathbf{x} is the associated eigen-vector, then

$$A^T A \mathbf{x} = \lambda \mathbf{x}$$

Multiply A on both sides,

$$AA^T (A \mathbf{x}) = \lambda (A \mathbf{x})$$

It can be seen that, λ and $A \mathbf{x}$ are eigen-value and the associated eigen-vector of AA^T



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Singular Value Decomposition's General Form

SVD decomposition theorem: Any matrix $A_{m \times n}$ can be decomposed as the following form,

$$A_{m \times n} = U_{m \times m} \Sigma_{m \times n} V_{n \times n}^T$$

where U and V are two orthogonal matrices, $r(A) = r$,

$$\Sigma_{m \times n} = \begin{bmatrix} \Sigma_r & \mathbf{O}_{r \times (n-r)} \\ \mathbf{O}_{(m-r) \times r} & \mathbf{O}_{(m-r) \times (n-r)} \end{bmatrix}_{m \times n} = \begin{bmatrix} \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_r \end{bmatrix} & \mathbf{O}_{r \times (n-r)} \\ \mathbf{O}_{(m-r) \times r} & \mathbf{O}_{(m-r) \times (n-r)} \end{bmatrix}_{m \times n}$$

$\sigma_1, \sigma_2, \dots, \sigma_r > 0$ are called the **singular values** of A

In general case, $\Sigma_{m \times n}$ is not unique. However, if $\{\sigma_i\}_{i=1}^r$ are arranged in order, $\Sigma_{m \times n}$ is uniquely determined by A . In the following, we require that $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$



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Relationship between SVD and EVD

Result 5: Suppose that $rank(A_{m \times n}) = r$, then $(A^T A)_{n \times n}$ has and only has r positive eigen-values and all its other eigen-values are zeros

Proof:

$r(A_{m \times n}) = r \xrightarrow{\text{result 1}} r(A^T A) = r$
 $A^T A$ is a real symmetric matrix } $\xrightarrow{\text{result 2}}$ $A^T A$ has and only has r non-zero eigen-values

Using result 3, $A^T A$ is positive semi-definite \implies eigen-values of $A^T A$ are all non-negative

$A^T A$ has and only has r positive eigen-values
and all its other eigen-values are zeros



Relationship between SVD and EVD

If $A \in \mathbb{R}^{m \times n}$, $r(A_{m \times n}) = r$, using result 5, $A^T A$ can be orthogonally diagonalized as,
 (Note: $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > 0$ and V' is an orthogonal matrix)

$$(A^T A)_{n \times n} = V' \begin{bmatrix} \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_r \end{bmatrix} & \mathbf{O}_{r \times (n-r)} \\ \mathbf{O}_{(n-r) \times r} & \mathbf{O}_{(n-r) \times (n-r)} \end{bmatrix}_{n \times n} V'^T$$

On the other hand, based on SVD, we know that $A = U \Sigma V^T$, then

$$(A^T A)_{n \times n} = (U \Sigma_{m \times n} V^T)^T (U \Sigma_{m \times n} V^T) \\ = V \Sigma^T U^T U \Sigma V^T = V (\Sigma^T \Sigma)_{n \times n} V^T$$

$$= V \begin{bmatrix} \begin{bmatrix} \sigma_1^2 & & & \\ & \sigma_2^2 & & \\ & & \ddots & \\ & & & \sigma_r^2 \end{bmatrix} & \mathbf{O}_{r \times (n-r)} \\ \mathbf{O}_{(n-r) \times r} & \mathbf{O}_{(n-r) \times (n-r)} \end{bmatrix}_{n \times n} V^T$$



$$\sigma_i = \sqrt{\lambda_i}, 1 \leq i \leq r$$



Relationship between SVD and EVD

- We can have the following conclusions about the SVD of A and the EVD of $A^T A$
 - A has r singular values $\{\sigma_i\}_{i=1}^r$ (positive) and $A^T A$ has r positive eigen-values $\{\lambda_i\}_{i=1}^r$ (all its other eigen-values are zeros), and $\sigma_i = \sqrt{\lambda_i}$
 - A 's right singular matrix V is actually the orthogonal matrix V' obtained when performing orthogonally diagonalization to $A^T A$; but it needs to be noted that V (V') is not unique
- Using similar derivations, we can have the following conclusions about the SVD of A and the EVD of AA^T
 - AA^T has the same r positive eigen-values $\{\lambda_i\}_{i=1}^r$ (result 4), and $\sigma_i = \sqrt{\lambda_i}$
 - A 's left singular matrix U is actually the orthogonal matrix obtained when performing orthogonally diagonalization to AA^T ; but it needs to be noted that both of them are not unique



Relationship between SVD and EVD

- Consider the following special cases
 - If A is an $n \times n$ matrix, how about its eigen-values and singular values?
 - If A is an $n \times n$ real symmetric matrix, how about its eigen-values and singular values?
 - If A is an $n \times n$ real symmetric and positive semi-definite matrix, how about its eigen-values and singular values?



Relationship between SVD and EVD

Result 6: Suppose that $A_{n \times n}$ is a positive semi-definite (real symmetric) matrix. Then, its eigen-values and singular values are the same.

Proof:

Suppose that $rank(A) = r$

$A_{n \times n}$ is positive semi-definite (and real symmetric)

result 5



A has and only has r positive eigen-values $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > 0$ and all its other eigen-values are zeros



$$A = U \begin{bmatrix} \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_r \end{bmatrix} & O \\ O & O \end{bmatrix}_{n \times n}$$



U^T

$$A^T A = U \begin{bmatrix} \begin{bmatrix} \lambda_1^2 & & & \\ & \lambda_2^2 & & \\ & & \ddots & \\ & & & \lambda_r^2 \end{bmatrix} & O \\ O & O \end{bmatrix}_{n \times n}$$



U^T

A 's singular values are $\sigma_i = \sqrt{\lambda_i^2} = \lambda_i (1 \leq i \leq r)$



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Outer product form of SVD

Result 7: Outer product form of a matrix product.

In general, if X is an $m \times k$ matrix and Y is a $k \times n$ matrix, the matrix product can be expressed as,

$$XY = \sum_{i=1}^k [\text{col}(X)_i]_{m \times 1} [\text{row}(Y)_i]_{1 \times n}$$

Note: each submatrix $[\text{col}(X)_i][\text{row}(Y)_i]$ is of rank 1



Outer product form of SVD

Let's consider the economy-sized SVD of A , $A_{m \times n} = [\mathbf{u}_1, \dots, \mathbf{u}_r] \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_r \end{bmatrix} \begin{bmatrix} \mathbf{v}_1^T \\ \vdots \\ \mathbf{v}_r^T \end{bmatrix}$

Let $X = [\mathbf{u}_1, \dots, \mathbf{u}_r] \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_r \end{bmatrix} = (\sigma_1 \mathbf{u}_1, \sigma_2 \mathbf{u}_2, \dots, \sigma_r \mathbf{u}_r)$, $Y = \begin{bmatrix} \mathbf{v}_1^T \\ \mathbf{v}_2^T \\ \vdots \\ \mathbf{v}_r^T \end{bmatrix}$

$$A = XY = (\sigma_1 \mathbf{u}_1, \sigma_2 \mathbf{u}_2, \dots, \sigma_r \mathbf{u}_r) \begin{bmatrix} \mathbf{v}_1^T \\ \mathbf{v}_2^T \\ \vdots \\ \mathbf{v}_r^T \end{bmatrix} \xrightarrow{\text{result 6}} \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$$

Outer product form of SVD



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Matrix norms and singular values

Definition 1: The **spectral norm** of a matrix A is the largest singular value of A i.e. the square root of the largest eigenvalue of the positive semidefinite matrix $A^T A$ (or AA^T):

$$\|A\|_2 = \sqrt{\lambda_{\max}(A^T A)} = \sigma_{\max}(A)$$

Definition 2: The **nuclear norm** is the sum of all the singular values of A ,

$$\|A\|_* = \sum_{i=1}^{\text{rank}(A)} \sigma_i$$

Definition 3: The **Frobenius norm** of a matrix $A_{m \times n}$ is defined as,

$$\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n a_{ij}^2}$$



Matrix norms and singular values

Result 8: Suppose that $\text{rank}(A_{m \times n}) = r$ and $\sigma_1, \sigma_2, \dots, \sigma_r$ are A 's singular values, then

$$\|A\|_F = \sqrt{\sum_{i=1}^r \sigma_i^2}$$

Proof:

$$\|A\|_F = \sqrt{\text{trace}(A^T A)} = \sqrt{\text{trace}(AA^T)} = \sqrt{\sum_{i=1}^r \lambda_i} = \sqrt{\sum_{i=1}^r \sigma_i^2}$$

where $\lambda_1, \lambda_2, \dots, \lambda_r$ are the positive eigen-values of $A^T A$ (or AA^T)

Note: From result 5, we can know that $A^T A$ (or AA^T) has and only has r positive eigen-values and all the other eigen-values are zeros.



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SVD and linear least squares

Linear least squares is a general idea for solving linear equations,

$$A_{m \times n} \mathbf{x}_{n \times 1} = \mathbf{b}_{m \times 1} \quad (1)$$

Using the idea of least squares, Eq. 1 is equivalent to the following problem,

$$\mathbf{x}^* = \arg \min_{\mathbf{x}} \|A_{m \times n} \mathbf{x}_{n \times 1} - \mathbf{b}_{m \times 1}\|_2^2 \quad (2)$$

Eq. 2 can be solved by finding the stationary point \mathbf{x}^* of $\|A_{m \times n} \mathbf{x}_{n \times 1} - \mathbf{b}_{m \times 1}\|_2^2$, i.e.

\mathbf{x}^* should satisfy,

$$A^T A \mathbf{x}^* = A^T \mathbf{b} \quad (3)$$

In Eq. 3, when $\text{rank}(A) = n$ (the columns of A are linearly independent),

$\text{rank}(A^T A) = n \implies A^T A$ is invertible $\implies \mathbf{x}^*$ is uniquely determined as $\mathbf{x}^* = (A^T A)^{-1} A^T \mathbf{b}$

How about when $\text{rank}(A) < n$?



SVD and linear least squares

- For solving the linear least squares numerically with a computer, usually we do not use the form of Eq. (3) (though it is elegant) for two reasons
 - When $\text{rank}(A) < n$, \mathbf{x}^* can not be determined
 - Even though $A^T A$ is invertible, the formation of $A^T A$ can dramatically degrade the accuracy of the computation
- Instead, we can use the technique of SVD



SVD and linear least squares

Suppose the SVD form of A is,

$$A_{m \times n} = U_{m \times m} \Sigma_{m \times n} V_{n \times n}^T$$



$$A\mathbf{x} - \mathbf{b} = U\Sigma V^T \mathbf{x} - \mathbf{b} = U(\Sigma V^T \mathbf{x}) - U(U^T \mathbf{b}) \triangleq U(\Sigma \mathbf{y}_{n \times 1} - \mathbf{c}_{m \times 1})$$

where $\mathbf{y}_{n \times 1} = V^T \mathbf{x}$, $\mathbf{c}_{m \times 1} = U^T \mathbf{b}$

Since U is an orthogonal matrix,

$$\|A\mathbf{x} - \mathbf{b}\| = \|U(\Sigma \mathbf{y}_{n \times 1} - \mathbf{c}_{m \times 1})\| = \|\Sigma \mathbf{y}_{n \times 1} - \mathbf{c}_{m \times 1}\|$$

Then, our objective is to identify \mathbf{y} that can make $\|\Sigma \mathbf{y}_{n \times 1} - \mathbf{c}_{m \times 1}\|$ have minimum length



SVD and linear least squares

$$\Sigma \mathbf{y}_{n \times 1} = \begin{bmatrix} \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_r \end{bmatrix} & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(m-r) \times r} & \mathbf{0}_{(m-r) \times (n-r)} \end{bmatrix}_{m \times n} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} \sigma_1 y_1 \\ \sigma_2 y_2 \\ \vdots \\ \sigma_r y_r \\ 0 \\ \vdots \\ 0 \end{bmatrix}_{m \times 1} \rightarrow \Sigma \mathbf{y}_{n \times 1} - \mathbf{c}_{m \times 1} = \begin{bmatrix} \sigma_1 y_1 - c_1 \\ \sigma_2 y_2 - c_2 \\ \vdots \\ \sigma_r y_r - c_r \\ -c_{r+1} \\ \vdots \\ -c_m \end{bmatrix}_{m \times 1}$$

Then, we simply let $y_i = \frac{c_i}{\sigma_i}, 1 \leq i \leq r$; then, $\|\Sigma \mathbf{y}_{n \times 1} - \mathbf{c}_{m \times 1}\|$ can get the minimum length $\sqrt{\sum_{i=r+1}^m c_i^2}$

Note that $y_{r+1} \sim y_n$ can be arbitrary



SVD and linear least squares

The operation $y_i = \frac{c_i}{\sigma_i}, 1 \leq i \leq r$ can be simply completed by a matrix multiplication,

$$\mathbf{y} = \begin{bmatrix} \begin{bmatrix} 1 \\ \sigma_1 \\ \vdots \\ 1 \\ \mathbf{0}_{(n-r) \times r} \end{bmatrix} \begin{bmatrix} \mathbf{0}_{r \times (m-r)} \\ \mathbf{0}_{(n-r) \times (m-r)} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{bmatrix}_{m \times 1} \\ \begin{bmatrix} c_1 / \sigma_1 \\ c_2 / \sigma_2 \\ \vdots \\ c_r / \sigma_r \\ 0 \\ \vdots \\ 0 \end{bmatrix}_{n \times 1} \triangleq \Sigma^+ \mathbf{c}_{m \times 1}$$

where Σ^+ means transposing Σ and inverting all non-zero diagonal entries

Finally,

$$\mathbf{x} = V \mathbf{y}_{n \times 1} = V \Sigma^+ \mathbf{c}_{m \times 1} = V \Sigma^+ U^T \mathbf{b}$$

Moore-Penrose inverse



SVD and linear least squares

- Some notes about the generalized inverse used in linear least squares
 - It does not have requirements for the rank of A
 - It can guarantee that the obtained solution can make $\|A\mathbf{x} - \mathbf{b}\|$ having the minimum length; but **the solution may be not unique**

